



Thesis Project Form

Title (tentative): Reinforcement learning with spiking neural network models and chips

Thesis advisor(s): Sabatini Silvio P., Giacomo Indiveri (INI - ETH and University of Zurich, CH), Cristiano Capone (ISS, Roma)

E-mail: silvio.sabatini@unige.it

Address: Via All'Opera Pia, 13 - 16145 Genova (III piano)

Phone: (+39) 010 33 52092

Description

Motivation and application domain

Biologically inspired model that uses spiking neural networks combined with a "wake" and a "sleep" phase learning phase have been recently proposed and implemented.

General objectives and main activities

The goal of the thesis is to implement the neural dynamics in real-time onto the DYNAP-SE mixed-signal spiking neural network chip. The neural network chip will be interfaced to a computer in-the-loop that will be used to implement the reinforcement-learning protocol. The goal is to validate the model and verify its robustness to biologically relevant constraints, such as limited precision, low resolution, sensitivity to noise, and in-homogeneity of neuron and synapse circuits.

Accordingly, the main tasks will be the following ones:

- implement an on-chip a recurrent spiking network capable to learn in a supervised fashion the world model;
- build the agent-module that will be interfaced to a computer in-the-loop, which will be used to implement the reinforcement-learning protocol;
- validate the model and verify its robustness to biologically relevant constraints;
- benchmark the architecture on standard discrete control tasks.

Training Objectives (technical/analytical tools, experimental methodologies)

The student will learn to employ different methodologies and instrumentation, including:

- Modeling of spiking neural networks using the Python Brian neural network simulator
- Programming scalable multi-core dynamic neuromorphic asynchronous spiking neural network processors (DYNAP-SE)

Place(s) where the thesis work will be carried out: INI (ETH and University of Zurich)

Additional information

Maximum number of students: 1

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